

A STUDY ON $(\mathcal{L}cs)_n$ -MANIFOLDS INDUCED WITH \mathcal{SVK} -CONNECTION

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Abstract: The present paper aims to define and discuss $(\mathcal{L}cs)_n$ -manifolds and Schouten van Kampen connection. We discussed the curvature tensor and Ricci curvature tensor of this manifold with respect to the \mathcal{SVK} -connection. We studied conformally flat, projectively flat, conharmonically flat, and concircularly flat $(\mathcal{L}cs)_n$ -manifolds with the \mathcal{SVK} -connection. At last, we gave an example of $(\mathcal{L}cs)_n$ -manifolds with \mathcal{SVK} -connection.

Keywords and Phrases: $(\mathcal{L}cs)_n$ -manifold, \mathcal{SVK} -connection.

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1. Introduction

In 1989, K. Matsumoto [6] introduced the notion of Lorentzian para-Sasakian manifolds and the generalization of LP -Sasakian manifolds. Lorentzian concircular structure manifolds (shortly, $(\mathcal{L}cs)_n$ -manifolds) were introduced in 2003 by A. A. Shaikh [9]. In 2005 and 2006, Shaikh and Baishya [10], [11] investigated the application of $(\mathcal{L}cs)_n$ -manifolds to the general theory of relativity and cosmology. $(\mathcal{L}cs)_n$ -manifolds are also studied by Atceken et al ([1], [2]), D Narain and S, Yadav [13].

The \mathcal{SVK} -connection, endowed with an affine connection, is one of the most natural connections adapted to a pair of distributions on a differentiable manifold [3], [8]. Solov'ev [12] investigated hyperdistributions in Riemannian manifolds using the \mathcal{SVK} -connection. Then, Zbigniew Olszak [7] studied the Schouten-van Kampen

affine connection in relation to an almost contact metric structure and obtained certain curvature properties of this connection on the manifold. Ahmet Yildiz [14], Semra Zeren [15], M. Manev [5], and others also studied \mathcal{SVK} -connection on different manifolds such as f -Kenmotsu manifolds, LP -Sasakian manifolds.

2. Preliminaries

In a Lorentzian manifold (\mathcal{M}, g) , we define a vector field ρ and 1-form \mathcal{A} as

$$\mathcal{A}(X) = g(X, \rho), \quad (2.1)$$

for any vector field $X \in \chi(\mathcal{M})$. This ρ is called a concircular vector field [15] if

$$(\nabla_{X_1} \mathcal{A})(X_2) = \alpha \{g(X_1, X_2) + \omega(X_1)A(X_2)\}, \quad (2.2)$$

where α is a non-zero scalar function and ω is a closed 1-form.

Let \mathcal{M} be a Lorentzian manifold admitting a unit timelike concircular vector field ξ , called the generator of the manifold, Then we have

$$g(\xi, \xi) = -1 \quad (2.3)$$

Since ξ is the unit concircular vector field, there exists a non-zero 1-form η so that for

$$g(X, \xi) = \eta(X) \quad (2.4)$$

following equations

$$(\nabla_{X_1} \eta)(X_2) = \alpha [g(X_1, X_2) + \eta(X_1)\eta(X_2)] \quad (2.5)$$

and

$$\nabla_X \xi = \alpha [X + \eta(X)\xi] \quad (2.6)$$

hold for all vector fields X, X_1, X_2 on \mathcal{M} , where ∇ denotes the covariant derivative with respect to Lorentzian metric g and α is non-zero scalar function satisfying

$$\nabla_X \alpha = (X\alpha) = d\alpha(X) = \rho\eta(X), \quad (2.7)$$

where ρ is a certain scalar function given by $\rho = -(\xi\alpha)$.

If we put

$$\phi X = \frac{1}{\alpha} \nabla_X \xi, \quad (2.8)$$

Then from (2.5) and (2.8) we say that

$$\phi X = X + \eta(X)\xi, \quad (2.9)$$

from which we have that ϕ is a symmetric $(1,1)$ tensor field and is called the structure tensor of the manifold. Thus the Lorentzian manifold \mathcal{M} together with unit timelike concircular vector field ξ , its associate 1-form η and $(1,1)$ -tensor field ϕ , is said to be Lorentzian concircular structure manifold $(\mathcal{M}, g, \phi, \xi, \eta, \alpha)$ (briefly, $(\mathcal{Lcs})_n$ -manifold) [9]. In particular if $\alpha=1$, we obtain LP -Sasakian structure manifold [4].

A differentiable manifold \mathcal{M} of dimension n is known to be $(\mathcal{Lcs})_n$ -manifold if it admits a $(1,1)$ -type tensor field ϕ , a covariant vector field η and a Lorentzian metric g which satisfy

$$\begin{aligned}\phi^2 X &= X + \eta(X)\xi, \\ \eta \circ \phi &= 0, \\ \phi \xi &= 0, \\ \eta(\xi) &= -1, \\ g(\phi X_1, \phi X_2) &= g(X_1, X_2) + \eta(X_1)\eta(X_2)\end{aligned}\tag{2.10}$$

for all $X_1, X_2 \in \chi(\mathcal{M})$. In an $(\mathcal{Lcs})_n$ -manifold \mathcal{M} , we have the following relations

$$(\nabla_{X_1} \phi)X_2 = \alpha[g(X_1, X_2)\xi + 2\eta(X_1)\eta(X_2)\xi + \eta(X_2)X_1]\tag{2.11}$$

$$\eta(\mathcal{R}(X_1, X_2)X_3) = (\alpha^2 - \rho)[g(X_2, X_3)\eta(X_1) - g(X_1, X_3)\eta(X_2)],\tag{2.12}$$

$$\mathcal{R}(X_1, X_2)\xi = (\alpha^2 - \rho)[\eta(X_2)X_1 - \eta(X_1)X_2],\tag{2.13}$$

$$\mathcal{R}(\xi, X)\xi = (\alpha^2 - \rho)(\eta(X)\xi + X),\tag{2.14}$$

$$\mathcal{S}(X, \xi) = (n-1)(\alpha^2 - \rho)\eta(X).\tag{2.15}$$

$$QX = (n-1)(\alpha^2 - \rho)X.\tag{2.16}$$

$$\mathcal{S}(\phi X_1, \phi X_2) = (n-1)(\alpha^2 - \rho)g(\phi X_1, \phi X_2).\tag{2.17}$$

for any vector fields $X, X_1, X_2, X_3 \in \chi(\mathcal{M})$. \mathcal{R} being the curvature tensor and \mathcal{S} being the Ricci tensor.

Definition 2.1. An n -dimensional pseudo-Riemannian manifold is said to be an η -Einstein manifold if the Ricci tensor of the manifold satisfies the condition

$$\mathcal{S}(X_1, X_2) = ag(X_1, X_2) + b\eta(X_1)\eta(X_2).\tag{2.18}$$

If $b = 0$, the manifold is an Einstein manifold.

If $a = 0$, the manifold is a special type of η -Einstein manifold.

3. Schouten-van Kampen connection

Let U_1 and U_2 be two complementary distributions on a connected pseudo-Riemannian manifold of an arbitrary signature $(p, n-p)$, $0 \leq p \leq n$, $n = \dim \mathcal{M} \geq 2$, such that $\dim(U_1) = (n-1)$ and $\dim(U_2) = 1$ and the distribution U_2 is non-null. Then we have $TM = U_1 \otimes U_2$, Also $U_1 \cap U_2 = \{0\}$ and $U_1 \perp U_2$ such that

$$U_1 = \ker \eta, \quad U_2 = \text{span}\{\xi\}$$

where η is a linear form and ξ is unit vector field such that $\eta(X) = \epsilon g(X, \xi)$. Moreover, it holds that $\nabla_X \xi \in U_1$.

For any $X \in TM$, if X^{u_1} and X^{u_2} are the projections of X onto U_1 and U_2 .

We have

$$X = X^{u_1} + X^{u_2}$$

with

$$X^{u_1} = X - \eta(X)\xi,$$

and

$$X^{u_2} = \eta(X)\xi.$$

The \mathcal{SVK} -connection $\bar{\nabla}$ associated with Levi-Civita connection ∇ and adapted to the pair of the distribution (U_1, U_2) is defined by [3]

$$\bar{\nabla}_{X_1} X_2 = (\nabla_{X_1} X_2^{u_1})^{u_1} + (\nabla_{X_1} X_2^{u_2})^{u_2}. \quad (3.1)$$

From the above equation, we have

$$(\nabla_{X_1} X_2^{u_1})^{u_1} = \nabla_{X_1} X_2 - \eta(\nabla_{X_1} X_2)\xi - \eta(X_2) \nabla_{X_1} \xi. \quad (3.2)$$

and

$$(\nabla_{X_1} X_2^{u_2})^{u_2} = (\nabla_{X_1} \eta)(X_2)\xi + \eta(\nabla_{X_1} X_2)\xi. \quad (3.3)$$

Thus, the \mathcal{SVK} -connection with the help of Levi-Civita connection is being expressed as [8]

$$\bar{\nabla}_{X_1} X_2 = \nabla_{X_1} X_2 - \eta(X_2) \nabla_{X_1} \xi + (\nabla_{X_1} \eta)(X_2)\xi. \quad (3.4)$$

Thus, with the help of \mathcal{SVK} -connection, one can characterize many properties of some geometric objects, which are connected with the distributions U_1, U_2 . We compute that g, ξ, η are parallel with respect to $\bar{\nabla}$, that is $\bar{\nabla}g = 0$, $\bar{\nabla}\xi = 0$, $\bar{\nabla}\eta = 0$. Also the torsion \bar{T} of connection $\bar{\nabla}$ is given as [12]

$$\bar{T}(X_1, X_2) = \eta(X_1) \nabla_{X_2} \xi - \eta(X_2) \nabla_{X_1} \xi - 2d\eta(X_1, X_2)\xi. \quad (3.5)$$

4. Curvature tensor on $(\mathcal{Lcs})_n$ -manifolds with \mathcal{SVK} -connection

Let \mathcal{M} be an $(\mathcal{Lcs})_n$ -manifold with \mathcal{SVK} -connection. Then using (2.5), (2.6) in (3.2), we have the \mathcal{SVK} -connection $\bar{\nabla}$ associated to the Levi-Civita connection ∇ as

$$\bar{\nabla}_{X_1} X_2 = \nabla_{X_1} X_2 - \alpha \eta(X_2) X_1 + \alpha g(X_1, X_2) \xi \quad (4.1)$$

Let \mathcal{R} and $\bar{\mathcal{R}}$ be curvature tensors of Levi-Civita connection ∇ and the \mathcal{SVK} -connection $\bar{\nabla}$,

$$\bar{\mathcal{R}}(X_1, X_2) X_3 = \bar{\nabla}_{X_1} \bar{\nabla}_{X_2} X_3 - \bar{\nabla}_{X_2} \bar{\nabla}_{X_1} X_3 - \bar{\nabla}_{[X_1, X_2]} X_3 \quad (4.2)$$

Using (4.1), together with (2.5), (2.6), and (2.10), we obtain

$$\begin{aligned} \bar{\nabla}_{X_1} \bar{\nabla}_{X_2} X_3 = & \nabla_{X_1} \nabla_{X_2} X_3 + (\rho + 2\alpha^2) \eta(X_1) g(X_2, X_3) \xi + \alpha (X_1 g(X_2, X_3)) \xi \\ & + 2\alpha^2 g(X_2, X_3) X_1 - \alpha (X_1 \eta(X_3)) X_2 - \alpha \eta(X_3) \nabla_{X_1} X_2 \\ & + \alpha g(X_1, \nabla_{X_2} X_3) \xi - \alpha \eta(\nabla_{X_2} X_3) X_1 + \alpha^2 \eta(X_3) \eta(X_2) X_1 \\ & - \rho \eta(X_3) \eta(X_1) X_2, \end{aligned} \quad (4.3)$$

$$\begin{aligned} \bar{\nabla}_{X_2} \bar{\nabla}_{X_1} X_3 = & \nabla_{X_2} \nabla_{X_1} X_3 + (\rho + 2\alpha^2) \eta(X_2) g(X_1, X_3) \xi + \alpha (X_2 g(X_1, X_3)) \xi \\ & + 2\alpha^2 g(X_1, X_3) X_2 - \alpha (X_2 \eta(X_3)) X_1 - \alpha \eta(X_3) \nabla_{X_2} X_1 \\ & + \alpha g(X_2, \nabla_{X_1} X_3) \xi - \alpha \eta(\nabla_{X_1} X_3) X_2 + \alpha^2 \eta(X_3) \eta(X_1) X_2 \\ & - \rho \eta(X_3) \eta(X_2) X_1, \end{aligned} \quad (4.4)$$

$$\begin{aligned} \bar{\nabla}_{[X_1, X_2]} X_3 = & \nabla_{[X_1, X_2]} X_3 + \alpha g(\nabla_{X_1} X_2, X_3) \xi - \alpha g(\nabla_{X_2} X_1, X_3) \xi \\ & - \alpha \eta(X_3) \nabla_{X_1} X_2 + \alpha \eta(X_3) \nabla_{X_2} X_1. \end{aligned} \quad (4.5)$$

Using (4.3), (4.4) and (4.5) in (4.2), we have

$$\begin{aligned} \bar{\mathcal{R}}(X_1, X_2) X_3 = & \mathcal{R}(X_1, X_2) X_3 + 3\alpha^2 [g(X_2, X_3) X_1 - g(X_1, X_3) X_2] \\ & + (\rho + 2\alpha^2) [\eta(X_1) g(X_2, X_3) \xi - \eta(X_2) g(X_1, X_3) \xi \\ & + \eta(X_2) \eta(X_3) X_1 - \eta(X_1) \eta(X_3) X_2]. \end{aligned} \quad (4.6)$$

By putting $X_3 = \xi$ in (4.6), we have

$$\bar{\mathcal{R}}(X_1, X_2) \xi = 2(\alpha^2 - \rho)(\eta(X_2) X_1 - \eta(X_1) X_2). \quad (4.7)$$

Taking inner product with ξ in (4.6), we have

$$\eta(\bar{\mathcal{R}}(X_1, X_2) X_3) = 2(\alpha^2 - \rho)(g(X_2, X_3) \eta(X_1) - g(X_1, X_3) \eta(X_2)). \quad (4.8)$$

On contracting (4.6), we have Ricci tensor $\bar{\mathcal{S}}$ of an $(\mathcal{Lcs})_n$ -manifold with respect to the \mathcal{SVK} -connection $\bar{\nabla}$ as

$$\begin{aligned}\bar{\mathcal{S}}(X_1, X_2) = & \mathcal{S}(X_1, X_2) + [\alpha^2(3n - 5) - \rho]g(X_1, X_2) \\ & + (n - 2)(2\alpha^2 + \rho)\eta(X_1)\eta(X_2).\end{aligned}\quad (4.9)$$

$$\bar{\mathcal{S}}(X_1, \xi) = 2(n - 1)(\alpha^2 - \rho)\eta(X_1). \quad (4.10)$$

Again the Ricci operator $\bar{\mathcal{Q}}$ of an $(\mathcal{Lcs})_n$ -manifold with respect to the \mathcal{SVK} -connection $\bar{\nabla}$ is given as

$$\bar{\mathcal{Q}}X_1 = \mathcal{Q}X_1 + [\alpha^2(3n - 5) - \rho]X_1 + (n - 2)(2\alpha^2 + \rho)\eta(X_1)\xi. \quad (4.11)$$

where $\bar{\mathcal{S}}(X_1, X_2) = g(\bar{\mathcal{Q}}X_1, X_2)$.

Now, contracting (4.9) with respect to X_1 and X_2 , we have the scalar curvature \bar{r} of the $(\mathcal{Lcs})_n$ -manifold with respect to the \mathcal{SVK} -connection $\bar{\nabla}$ as

$$\bar{r} = r + (n - 1)(3n - 4)\alpha^2 - 2(n - 1)\rho. \quad (4.12)$$

where r is scalar curvature with respect to Levi-Civita connection ∇ .

5. Projectively flat $(\mathcal{Lcs})_n$ -manifolds with \mathcal{SVK} -connection

The projective curvature tensor \bar{P} with respect to the \mathcal{SVK} -connection $\bar{\nabla}$ is defined as

$$\bar{P}(X_1, X_2)X_3 = \bar{\mathcal{R}}(X_1, X_2)X_3 - \frac{1}{n - 1}[\bar{\mathcal{S}}(X_2, X_3)X_1 - \bar{\mathcal{S}}(X_1, X_3)X_2]. \quad (5.1)$$

A manifold is said to be projectively flat if

$$\bar{P}(X_1, X_2)X_3 = 0. \quad (5.2)$$

From equations (5.1) and (5.2), we have

$$\bar{\mathcal{R}}(X_1, X_2)X_3 = \frac{1}{n - 1}[\bar{\mathcal{S}}(X_2, X_3)X_1 - \bar{\mathcal{S}}(X_1, X_3)X_2]. \quad (5.3)$$

Taking inner product in (5.3) with ξ , we get

$$g(\bar{\mathcal{R}}(X_1, X_2)X_3, \xi) = \frac{1}{n - 1}[\bar{\mathcal{S}}(X_2, X_3)g(X_1, \xi) - \bar{\mathcal{S}}(X_1, X_3)g(X_2, \xi)]. \quad (5.4)$$

Using (4.8) and (5.4), we get

$$\begin{aligned}2(\alpha^2 - \rho)(g(X_2, X_3)\eta(X_1) - g(X_1, X_3)\eta(X_2)) &= \frac{1}{n - 1}[\bar{\mathcal{S}}(X_2, X_3)\eta(X_1) \\ &\quad - \bar{\mathcal{S}}(X_1, X_3)\eta(X_2)].\end{aligned}$$

Putting $X_1 = \xi$, the above equation takes form

$$2(\alpha^2 - \rho)[-g(X_2, X_3)) - \eta(X_2)\eta(X_3)] = \frac{1}{n-1}[-\bar{\mathcal{S}}(X_2, X_3) - 2(n-1)(\alpha^2 - \rho)\eta(X_2)\eta(X_3)].$$

Solving, we have the following:

Theorem 5.1. *A projectively flat $(\mathcal{L}cs)_n$ -manifold with \mathcal{SVK} -connection is an Einstein manifold.*

An $(\mathcal{L}cs)_n$ -manifolds with \mathcal{SVK} -connection is said to be ϕ -projectively flat if

$${}'\bar{P}(\phi X_1, \phi X_2, \phi X_3, \phi X_4) = 0, \quad (5.5)$$

where $X_1, X_2, X_3, X_4 \in \chi(\mathcal{M})$.

By (5.1), we have

$$\begin{aligned} {}'\bar{P}(X_1, X_2, X_3, X_4) &= {}'\bar{\mathcal{R}}(X_1, X_2, X_3, X_4) \\ &\quad - \frac{1}{n-1}[\bar{\mathcal{S}}(X_2, X_3)g(X_1, X_4) - \bar{\mathcal{S}}(X_1, X_3)g(X_2, X_4)], \end{aligned}$$

where ${}'\bar{P}(X_1, X_2, X_3, X_4) = g(\bar{P}(X_1, X_2)X_3, X_4)$ and ${}'\bar{\mathcal{R}}(X_1, X_2, X_3, X_4) = g(\bar{\mathcal{R}}(X_1, X_2)X_3, X_4)$.

Now putting $X_1 = \phi X_1, X_2 = \phi X_2, X_3 = \phi X_3, X_4 = \phi X_4$ in above and using (5.5), we have

$$\begin{aligned} {}'\bar{\mathcal{R}}(\phi X_1, \phi X_2, \phi X_3, \phi X_4) &= \frac{1}{n-1}[\bar{\mathcal{S}}(\phi X_2, \phi X_3)g(\phi X_1, \phi X_4) \\ &\quad - \bar{\mathcal{S}}(\phi X_1, \phi X_3)g(\phi X_2, \phi X_4)]. \end{aligned} \quad (5.6)$$

Let $\{\phi e_1, \phi e_2, \dots, \phi e_{n-1}, \xi\}$ be the local orthonormal basis of vector fields in M . Putting $X_1 = X_4 = e_i$ in (5.6) and taking summation over $i = 1$ to $n-1$, we have

$$\begin{aligned} \sum_{i=1}^{n-1} {}'\bar{\mathcal{R}}(\phi e_1, \phi X_2, \phi X_3, \phi e_4) &= \frac{1}{n-1}[\bar{\mathcal{S}}(\phi X_2, \phi X_3) \sum_{i=1}^{n-1} g(\phi e_1, \phi e_4) \\ &\quad - \sum_{i=1}^{n-1} \bar{\mathcal{S}}(\phi e_1, \phi X_3)g(\phi X_2, \phi e_4)]. \end{aligned} \quad (5.7)$$

Solving the above, we have

$$\bar{\mathcal{S}}(\phi X_2, \phi X_3) = \frac{1}{n-1}[(n-1)\bar{\mathcal{S}}(\phi X_2, \phi X_3) - g(\bar{\mathcal{Q}}\phi X_2, \phi X_3)],$$

which yields

$$\bar{\mathcal{S}}(\phi X_2, \phi X_3) = 0 = g(\bar{Q}\phi X_2, \phi X_3). \quad (5.8)$$

Using $\bar{Q}\phi = \phi\bar{Q} = \phi Q + [(3n-5)\alpha^2 - \rho]$ in (5.8)

$$g(\phi Q X_2, \phi X_3) + [(3n-5)\alpha^2 - \rho]g(\phi X_2, \phi X_3) = 0. \quad (5.9)$$

Using (2.10) and (2.16), (5.9) reduces to

$$S(X_2, X_3) = [\rho - (3n-5)\alpha^2]g(X_2, X_3) + [n\rho - 2(2n-3)\alpha^2]\eta(X_2)\eta(X_3). \quad (5.10)$$

From (4.9) and (5.10), we obtain

$$\bar{\mathcal{S}}(X_2, X_3) = 2(n-1)(\rho - \alpha^2)\eta(X_2)\eta(X_3). \quad (5.11)$$

Thus, we state the following

Theorem 5.2. *A ϕ -projectively flat $(\mathcal{Lcs})_n$ -manifold with \mathcal{SVK} -connection is a special type of η -Einstein manifold.*

6. Conformally flat $(\mathcal{Lcs})_n$ -manifolds with \mathcal{SVK} -connection

The Weyl conformal curvature tensor \bar{C} of type $(1, 3)$ of an n -dimensional Riemannian manifold is given as

$$\begin{aligned} \bar{C}(X_1, X_2)X_3 = & \mathcal{R}(X_1, X_2)X_3 \\ & - \frac{1}{(n-2)} [\bar{\mathcal{S}}(X_2, X_3)X_1 - \bar{\mathcal{S}}(X_1, X_3)X_2 \\ & + g(X_2, X_3)\bar{Q}X_1 - g(X_1, X_3)\bar{Q}X_2] \\ & + \frac{r}{(n-1)(n-2)} [g(X_2, X_3)X_1 - g(X_1, X_3)X_2] \end{aligned} \quad (6.1)$$

Let us suppose that $(\mathcal{Lcs})_n$ -manifold is Conformally flat with respect to the \mathcal{SVK} -connection, we have

$$\bar{C}(X_1, Y)X_3 = 0. \quad (6.2)$$

Using equation (6.1) and (6.2)

$$\begin{aligned} \bar{\mathcal{R}}(X_1, X_2)X_3 = & \frac{1}{(n-2)} [\bar{\mathcal{S}}(X_2, X_3)X_1 - \bar{\mathcal{S}}(X_1, X_3)Y \\ & + g(X_2, X_3)\bar{Q}X - g(X_1, X_3)\bar{Q}X_2] \\ & - \frac{\bar{r}}{(n-1)(n-2)} [g(X_2, X_3)X_1 - g(X_1, X_3)X_2]. \end{aligned} \quad (6.3)$$

Taking inner product with X_4

$$\begin{aligned} g(\bar{R}(X_1, X_2)X_3, X_4) &= \frac{1}{(n-2)} [\bar{\mathcal{S}}(X_2, X_3)g(X_1, X_4) - \bar{\mathcal{S}}(X_1, X_3)g(X_2, X_4) \\ &\quad + g(X_2, X_3)\bar{\mathcal{S}}(X_1, X_4) - g(X_1, X_3)\bar{\mathcal{S}}(X_2, X_4)] \\ &\quad - \frac{\bar{r}}{(n-1)(n-2)} [g(X_2, X_3)g(X_1, X_4) \\ &\quad - g(X_1, X_3)g(X_2, X_4)]. \end{aligned} \quad (6.4)$$

Putting $X_4 = \xi$ and using equations (2.4) and (4.10), we have

$$\begin{aligned} \eta(\bar{R}(X_1, X_2)X_3) &= \frac{1}{(n-2)} [\bar{\mathcal{S}}(X_2, X_3)\eta(X_1) - \bar{\mathcal{S}}(X_1, X_3)\eta(X_2)] \\ &\quad + \left[\frac{2(n-1)(\alpha^2 - \rho)}{n-2} - \frac{\bar{r}}{(n-1)(n-2)} \right] \\ &\quad [g(X_2, X_3)\eta(X_1) - g(X_1, X_3)\eta(X_2)]. \end{aligned} \quad (6.5)$$

Using equation (4.8), above equation becomes

$$\begin{aligned} \bar{\mathcal{S}}(X_2, X_3)\eta(X_1) &= \bar{\mathcal{S}}(X_1, X_3)\eta(X_2) + \left[\frac{\bar{r}}{(n-1)} - 2(\alpha^2 - \rho) \right] \\ &\quad [g(X_2, X_3)\eta(X_1) - g(X_1, X_3)\eta(X_2)]. \end{aligned} \quad (6.6)$$

Using $X = \xi$ in (6.6) and using equations (4.10) and (2.3), we have

$$\begin{aligned} \bar{\mathcal{S}}(X_2, X_3) &= \left[\frac{\bar{r}}{(n-1)} - 2(\alpha^2 - \rho) \right] g(X_2, X_3) \\ &\quad + \left[\frac{\bar{r}}{(n-1)} - 2n(\alpha^2 - \rho) \right] \eta(X_2)\eta(X_3). \end{aligned} \quad (6.7)$$

Hence, we can state the following:

Theorem 6.1. *A conformally flat $(\mathcal{Lcs})_n$ -manifold with \mathcal{SVK} -connection is an η -Einstein manifold.*

7. Conharmonically flat $(\mathcal{Lcs})_n$ -manifolds with \mathcal{SVK} -connection

The conharmonic curvature tensor \bar{V} with respect to the \mathcal{SVK} -connection $\bar{\nabla}$ is defined as

$$\begin{aligned} \bar{V}(X_1, X_2)X_3 &= \bar{\mathcal{R}}(X_1, X_2)X_3 - [\bar{\mathcal{S}}(X_2, X_3)X_1 - \bar{\mathcal{S}}(X_1, X_3)X_2 \\ &\quad + g(X_2, X_3)\bar{Q}X_1 - g(X_1, X_3)\bar{Q}X_2]. \end{aligned} \quad (7.1)$$

A manifold is said to be conharmonically flat if

$$\bar{V}(X_1, X_2)X_3 = 0. \quad (7.2)$$

From equations (7.1) and (7.2), we have

$$\bar{\mathcal{R}}(X_1, X_2)X_3 = \bar{\mathcal{S}}(X_2, X_3)X - \bar{\mathcal{S}}(X_1, X_3)X_2 + g(X_2, X_3)\bar{Q}X_1 - g(X_1, X_3)\bar{Q}X_2. \quad (7.3)$$

Now using (4.6), (4.9) and (4.11)

$$\begin{aligned} \mathcal{R}(X_1, X_2)X_3 = & \mathcal{S}(X_2, X_3)X_1 - \mathcal{S}(X_1, X_3)X_2 \\ & + (\alpha^2(6n - 13) - 2\rho)[g(X_2, X_3)X_1 - g(X_1, X_3)X_2] \\ & + (n - 3)(2\alpha^2 + \rho)[g(X_2, X_3)\eta(X_1)\xi - g(X_1, X_3)\eta(X_2)\xi] \\ & + (n - 3)(2\alpha^2 + \rho)[\eta(X_2)\eta(X_3)X_1 - \eta(X_1)\eta(X_3)X_2] \\ & + [g(X_2, X_3)QX_1 - g(X_1, X_3)QX_2]. \end{aligned} \quad (7.4)$$

Put $X_1 = \xi$ and using (2.13), (2.15) and (2.16) in above, we get

$$\begin{aligned} (\alpha^2 - \rho)[g(X_2, X_3)\xi - \eta(X_3)X_2] = & \mathcal{S}(X_2, X_3)\xi + (5n\alpha^2 - 8\alpha^2 - 2\rho(1 - n)) \\ & \times g(X_2, X_3)\xi. \end{aligned} \quad (7.5)$$

Taking inner product with ξ , we have

$$\begin{aligned} \mathcal{S}(X_2, X_3) = & (9\alpha^2 - 5n\alpha^2 - 3\rho + 2n\rho)g(X_2, X_3) \\ & + (10\alpha^2 - 6n\alpha^2 + 3n\rho - 4\rho)\eta(X_2)\eta(X_3). \end{aligned} \quad (7.6)$$

Thus we have the following:

Theorem 7.1. *A conharmonically flat $(\mathcal{Lcs})_n$ -manifold with \mathcal{SVK} -connection is an η -Einstein manifold with the Levi-Civita connection.*

Again using (7.6) in (4.9), we obtain

$$\bar{\mathcal{S}}(X_2, X_3) = 2(2 - n)(\alpha^2 - \rho)g(X_2, X_3) + 2(3 - 2n)(\alpha^2 - \rho)\eta(X_2)\eta(X_3). \quad (7.7)$$

Thus, we state

Theorem 7.2. *A conharmonically flat $(\mathcal{Lcs})_n$ -manifold with \mathcal{SVK} -connection is an η -Einstein manifold.*

8. Concircularly flat $(\mathcal{Lcs})_n$ -manifolds with \mathcal{SVK} -connection

The concircular curvature tensor \check{C} with respect to the \mathcal{SVK} -connection $\bar{\nabla}$ is defined as

$$\check{C}(X_1, X_2)X_3 = \bar{\mathcal{R}}(X_1, X_2)X_3 - \frac{\bar{r}}{n(n-1)}[g(X_2, X_3)X_1 - g(X_1, X_3)X_2] \quad (8.1)$$

for all X_1, X_2, X_3 in \mathcal{M} .

Now assume that $(\mathcal{Lcs})_n$ -manifold is concircularly flat with \mathcal{SVK} -connection then

$$\check{C}(X_1, X_2)X_3 = 0 \quad (8.2)$$

It follows

$$\bar{\mathcal{R}}(X_1, X_2)X_3 = \frac{\bar{r}}{n(n-1)}[g(X_2, X_3)X_1 - g(X_1, X_3)X_2] \quad (8.3)$$

Using (2.10), (2.12), (4.6) and (4.12), we get

$$\left[\frac{r - (n-1)(4\alpha^2 + 3n\alpha^2 + 2\rho)}{n(n-1)} \right] [g(X_2, X_3)\eta(X_1) - g(X_1, X_3)\eta(X_2)] = 0. \quad (8.4)$$

This implies that either scalar curvature of the manifold is $r = (n-1)(4\alpha^2 + 3n\alpha^2 + 2\rho)$ or

$$g(X_2, X_3)\eta(X_1) - g(X_1, X_3)\eta(X_2) = 0. \quad (8.5)$$

Put $X_1 = \xi$ in (8.5) and using (2.10)

$$g(X_2, X_3) = -\eta(X_2)\eta(X_3) \quad (8.6)$$

Replace X_3 by QX_3 , we have

$$S(X_2, X_3) = -(n-1)(\alpha^2 - \rho)\eta(X_2)\eta(X_3). \quad (8.7)$$

Hence, we state a theorem.

Theorem 8.1. *For a concircularly flat $(\mathcal{Lcs})_n$ -manifold with \mathcal{SVK} -connection, either the scalar curvature is $(n-1)(4\alpha^2 + 3n\alpha^2 + 2\rho)$ or the manifold is special type of η -Einstein manifold.*

9. An example of $(\mathcal{Lcs})_n$ -manifolds with \mathcal{SVK} -connection

Considering a 3-dimensional smooth manifold $\mathcal{M} = \left\{ (x, y, z) \in R^3 : z \neq 0 \right\}$, with (x, y, z) , the standard coordinates. Let $\{e_1, e_2, e_3\}$ be linearly independent global frame on \mathcal{M} given by

$$e_1 = z^2 \frac{\partial}{\partial x}, \quad e_2 = z^2 \frac{\partial}{\partial y}, \quad e_3 = \frac{\partial}{\partial z} \quad (9.1)$$

Let g be the Lorentzian metric defined by

$$g(e_1, e_1) = g(e_2, e_2) = 1, \quad g(e_3, e_3) = -1, \quad g(e_1, e_2) = g(e_2, e_3) = g(e_3, e_1) = 0$$

and η be 1-form defined by $\eta(Z) = g(Z, e_3)$ for any $Z \in \chi(\mathcal{M})$.
Considering a (1,1) tensor field ϕ defined by

$$\phi(e_1) = -e_2, \quad \phi(e_2) = -e_1, \quad \phi(e_3) = 0.$$

Then using linearity of g and ϕ , we get

$$\begin{aligned} \eta(e_3) &= -1, \\ \phi^2(Z) &= Z + \eta(Z)e_3, \\ g(\phi Z, \phi W) &= g(Z, W) + \eta(Z)\eta(W). \end{aligned}$$

for any $Z, W \in \chi(\mathcal{M})$. Now, by computation directly, we get

$$[e_1, e_3] = -\frac{2}{z}e_1, \quad [e_1, e_3] = -\frac{2}{z}e_1, \quad [e_1, e_2] = 0.$$

Using Koszul's formula for the Lorentzian metric g , we have

$$\begin{aligned} \nabla_{e_1}e_3 &= -\frac{2}{z}e_1, & \nabla_{e_2}e_3 &= -\frac{2}{z}e_2, & \nabla_{e_3}e_3 &= 0, \\ \nabla_{e_1}e_2 &= 0, & \nabla_{e_2}e_2 &= \frac{2}{z}e_3, & \nabla_{e_3}e_2 &= 0, \\ \nabla_{e_1}e_1 &= \frac{2}{z}e_3, & \nabla_{e_2}e_1 &= 0 & \nabla_{e_3}e_1 &= 0. \end{aligned} \tag{9.2}$$

From the above it can be easily seen that $e_3 = \xi$ is a unit timelike concircular vector field and hence $(\phi, \xi, \eta, g, \alpha)$ is an $(Lcs)_3$ -structure on \mathcal{M} . Consequently $\mathcal{M}^3(\phi, \xi, \eta, g, \alpha)$ is an $(Lcs)_3$ -manifold with $\alpha = -\frac{2}{z} \neq 0$ such that $(X\alpha) = \rho\eta(X)$ where $\rho = \frac{2}{z^2}$.

Using the above relations, we calculate components of curvature tensor R as follows:

$$\begin{aligned} R(e_1, e_3)e_3 &= -\frac{6}{z^2}e_1, & R(e_2, e_3)e_3 &= -\frac{6}{z^2}e_2, \\ R(e_i, e_j)e_3 &= 0, & R(e_i, e_j)e_j &= -\frac{4}{z^2}e_i, \quad i, j = 1, 2 \\ R(e_1, e_3)e_2 &= 0, & R(e_2, e_3)e_1 &= 0, & R(e_3, e_i)e_i &= -\frac{6}{z^2}e_3. \end{aligned} \tag{9.3}$$

Now the \mathcal{SVK} -connection on \mathcal{M} is given as

$$\begin{aligned}\bar{\nabla}_{e_1}e_3 &= -\left(\frac{2}{z} + \alpha\right)e_1, & \bar{\nabla}_{e_2}e_3 &= -\left(\frac{2}{z} + \alpha\right)e_2, & \bar{\nabla}_{e_3}e_3 &= \alpha(e_3 - \xi), \\ \bar{\nabla}_{e_1}e_2 &= 0, & \bar{\nabla}_{e_2}e_2 &= \frac{2}{z}e_3 + \alpha\xi, & \bar{\nabla}_{e_3}e_2 &= 0, \\ \bar{\nabla}_{e_1}e_1 &= \frac{2}{z}e_3 + \alpha\xi, & \bar{\nabla}_{e_2}e_1 &= 0 & \bar{\nabla}_{e_3}e_1 &= 0.\end{aligned}\tag{9.4}$$

From (9.4) we have that $\bar{\nabla}_{e_i}e_j = 0$ ($1 \leq i, j \leq 3$) for $\xi = e_3$ and $\alpha = -\frac{2}{z}$. Hence \mathcal{M} is a 3-dimensional $(\mathcal{Lcs})_n$ -manifold with \mathcal{SVK} -connection.

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